

**Exercise Sheet 9 to the Lecture Course “Computational Finance”**  
(B-Spline and Hat-Functions)

**Task 1 (Cubic B-Spline)** (3+3+1 Points)

Suppose an equidistant partition of an interval be given with mesh-size  $h = x_{k+1} - x_k$ . Cubic  $B$ -splines have a support of four subintervals. In each subinterval the spline is a piece of polynomial of degree three. Apart from special boundary splines, the cubic  $B$ -splines  $\varphi_i$  are determined by the requirements

$$\begin{aligned}\varphi_i(x_i) &= 1 \\ \varphi_i(x) &\equiv 0 \quad \text{for } x < x_{i-2} \\ \varphi_i(x) &\equiv 0 \quad \text{for } x > x_{i+2} \\ \varphi &\in C^2(\mathbb{R}).\end{aligned}$$

To construct the  $\varphi_i$  proceed as follows:

- a) Construct a spline  $S(x)$  that satisfies the above requirements for the special nodes

$$\tilde{x}_k := 2 + k \quad \text{for } k = 0, 1, \dots, 4.$$

- b) Find a transformation  $T_i(x)$ , such that  $\varphi_i = S(T_i(x))$  satisfies the requirements for the original nodes.
- c) For which  $i, j$  does  $\varphi_i \varphi_j = 0$  hold?

**Task 2 (Finite-Element Matrices)** (3 Points)

For the hat functions  $\varphi$  from Section 5.2 calculate for arbitrary subinterval  $\mathcal{D}_k$  all nonzero integrals of the form

$$\int \varphi_i \varphi_j \, dx, \quad \int \varphi'_i \varphi_j \, dx, \quad \int \varphi'_i \varphi'_j \, dx$$

and represent them as local  $2 \times 2$  matrices.

- **Return** the solutions until Monday, January 16, **before** the lectures.